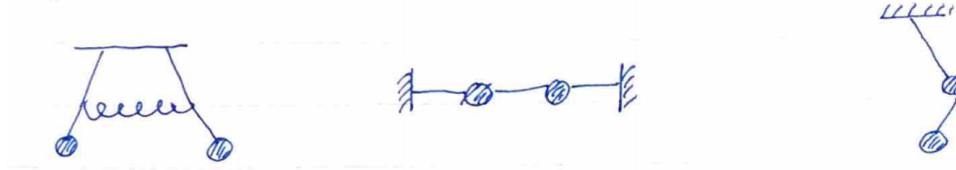


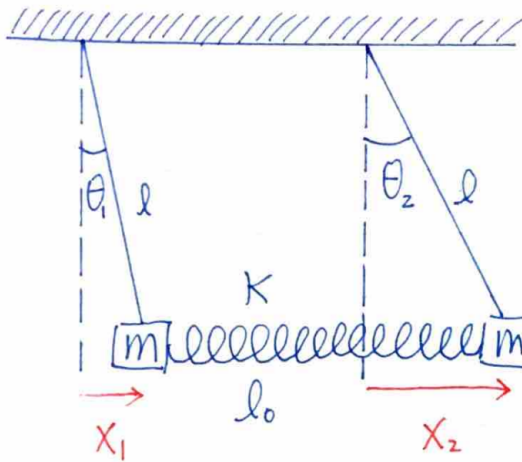
8.03 Lecture 6

Examples of coupled oscillations:



	Arbitrary Excitation	Normal Mode Excitation
Motion	Not Harmonic	Harmonic
Amplitude Ration	Varies	Constant
Energy	Migrates	stays

Next we will look at driven coupled oscillators.



Last time:

We solved the normal mode of this system. Now we would like to add a driving force on left mass.

$$\vec{F}_d = F_0 \cos(\omega_d t) \hat{x}$$

Equations of motion:

$$m\ddot{x}_1 = -\left(k + \frac{mg}{l}\right)x_1 + kx_2 + \mathbf{F}_0 \cos(\omega_d t)$$

$$m\ddot{x}_2 = kx_1 - \left(k + \frac{mg}{l}\right)x_2$$

Putting the equation of motion into matrix form we have:

$$M\ddot{X} = -KX + F \cos(\omega_d t)$$

where

$$M = \begin{pmatrix} m & 0 \\ 0 & m \end{pmatrix} \quad K = \begin{pmatrix} k + \frac{mg}{l} & -k \\ -k & k + \frac{mg}{l} \end{pmatrix} \quad X = \begin{pmatrix} x_1 \\ x_2 \end{pmatrix}$$

$$\Rightarrow \ddot{X} = -M^{-1}KX + M^{-1}F \cos(\omega_d t)$$

$$M^{-1}K = \begin{pmatrix} \frac{k}{m} + \frac{g}{l} & -\frac{k}{m} \\ -\frac{k}{m} & \frac{k}{m} + \frac{g}{l} \end{pmatrix} \quad M^{-1}F = \begin{pmatrix} \frac{F_0}{m} \\ 0 \end{pmatrix}$$

Last time we solved the homogeneous equation:

$$\det(M^{-1}K - \omega^2 I) = 0$$

Recall the solutions:

$$\omega_1^2 = \frac{g}{l} \quad A^{(1)} = \begin{pmatrix} 1 \\ 1 \end{pmatrix} \quad \text{and} \quad \omega_2^2 = \frac{g}{l} + \frac{2k}{m} \quad A^{(2)} = \begin{pmatrix} 1 \\ -1 \end{pmatrix}$$

$$\det(M^{-1}K - \omega^2 I) = (\omega^2 - \omega_1^2)(\omega^2 - \omega_2^2) = 0$$

Homogeneous solution:

$$x = \alpha \begin{pmatrix} 1 \\ 1 \end{pmatrix} \cos(\omega_1 t + \phi_1) + \beta \begin{pmatrix} 1 \\ -1 \end{pmatrix} \cos(\omega_2 t + \phi_2)$$

Now we have an additional driving force:

$$\ddot{X} + M^{-1}KX = M^{-1}F \cos(\omega_d t)$$

Similar to driven oscillator problem, we want to eliminate the $\cos(\omega_d t)$ term...

Go to complex notation: $X = \text{Re}[Z]$ $\ddot{Z} + M^{-1}KZ = M^{-1}F e^{i\omega_d t}$

Guess: $Z = B e^{i\omega_d t}$ where $B = \begin{pmatrix} B_1 \\ B_2 \end{pmatrix}$

Plug our guess for Z into the equation:

$$\begin{aligned} \Rightarrow (M^{-1}K - \omega_d^2 I) B e^{i\omega_d t} &= M^{-1}F e^{i\omega_d t} \\ \Rightarrow (M^{-1}K - \omega_d^2 I) B &= M^{-1}F \end{aligned}$$

These are just two simultaneous equations:

$$\begin{pmatrix} \frac{k}{m} + \frac{g}{l} - \omega_d^2 & -\frac{k}{m} \\ -\frac{k}{m} & \frac{k}{m} + \frac{g}{l} - \omega_d^2 \end{pmatrix} \begin{pmatrix} B_1 \\ B_2 \end{pmatrix} = \begin{pmatrix} \frac{F_0}{m} \\ 0 \end{pmatrix}$$

$$\begin{aligned} \left(\frac{k}{m} + \frac{g}{l} - \omega_d^2 \right) B_1 - \frac{k}{m} B_2 &= \frac{F_0}{m} \\ -\frac{k}{m} B_1 + \left(\frac{k}{m} + \frac{g}{l} - \omega_d^2 \right) B_2 &= 0 \end{aligned}$$

We can go ahead and solve it directly to get B_1 and B_2 or we can use ‘‘Cramer’s Rule’’ which is a useful rule when solving a large number of coupled oscillators.

First define:

$$\overleftrightarrow{E} = \begin{pmatrix} \frac{k}{m} + \frac{g}{l} - \omega_d^2 & -\frac{k}{m} \\ -\frac{k}{m} & \frac{k}{m} + \frac{g}{l} - \omega_d^2 \end{pmatrix} \quad \vec{D} = \begin{pmatrix} \frac{F_0}{m} \\ 0 \end{pmatrix}$$

To use Cramer's rule, use one column from \overleftrightarrow{E} and \vec{D}

$$\begin{aligned}
 B_1 &= \frac{|(\vec{D})(\)|}{\det \overleftrightarrow{E}} \\
 &= \frac{\begin{pmatrix} \frac{F_0}{m} & \frac{-k}{m} \\ 0 & (\frac{k}{m} + \frac{g}{l} - \omega_d^2) \end{pmatrix}}{(\omega_d^2 - \omega_1^2)(\omega_d^2 - \omega_2^2)} \\
 &= \frac{\frac{F_0}{m} (\frac{k}{m} + \frac{g}{l} - \omega_d^2)}{(\omega_d^2 - \omega_1^2)(\omega_d^2 - \omega_2^2)}
 \end{aligned}$$

Which explodes when $\omega_d = \omega_1, \omega_2$ which are the frequencies of the normal modes. Similarly:

$$\begin{aligned}
 B_2 &= \frac{|(\)(\vec{D})|}{\det \overleftrightarrow{E}} \\
 &= \frac{\begin{pmatrix} \frac{k}{m} + \frac{g}{l} - \omega_d^2 & \frac{F_0}{m} \\ -\frac{k}{m} & 0 \end{pmatrix}}{(\omega_d^2 - \omega_1^2)(\omega_d^2 - \omega_2^2)} \\
 &= \frac{\frac{F_0}{m} (\frac{k}{m})}{(\omega_d^2 - \omega_1^2)(\omega_d^2 - \omega_2^2)}
 \end{aligned}$$

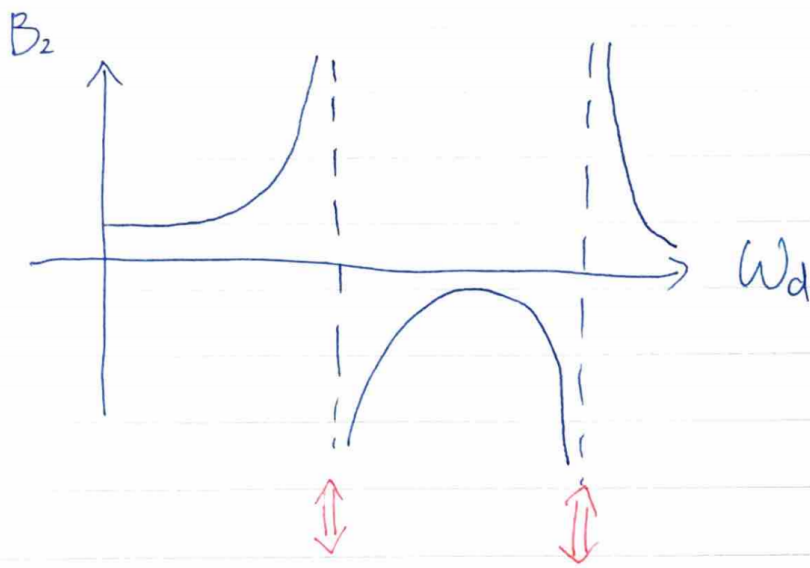
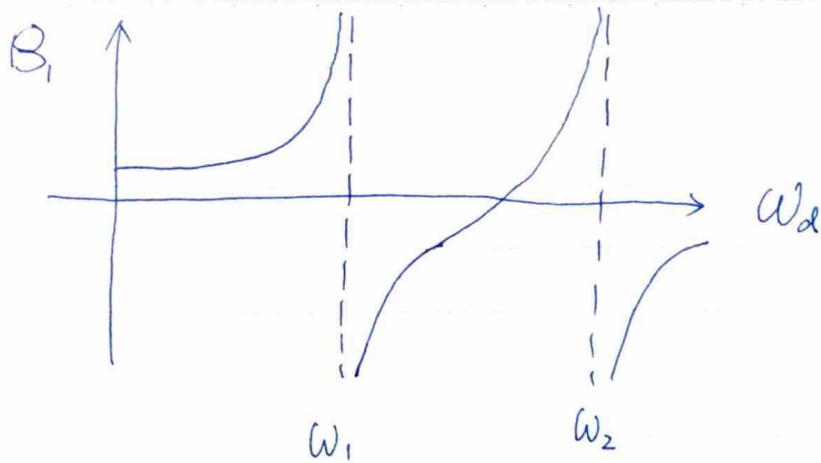
$$\frac{B_1}{B_2} = \frac{k/m + g/l - \omega_d^2}{k/m}$$

$$\begin{aligned}
 (1) \quad \omega_d^2 = \omega_1^2 &= \frac{g}{l} \Rightarrow \frac{B_1}{B_2} = 1 \\
 (2) \quad \omega_d^2 = \omega_2^2 &= \frac{g}{l} + \frac{2k}{m} \Rightarrow \frac{B_1}{B_2} = -1
 \end{aligned}$$

Full solution:

$$\begin{aligned}
 x_1 &= \alpha \cos(\omega_1 t + \phi_1) + \beta \cos(\omega_2 t + \phi_2) + B_1 \cos(\omega_d t) \\
 x_2 &= \alpha \cos(\omega_1 t + \phi_1) - \beta \cos(\omega_2 t + \phi_2) + B_2 \cos(\omega_d t)
 \end{aligned}$$

Where the term with B amplitude is the particular solution and the terms with α and β amplitude are the homogeneous solution.



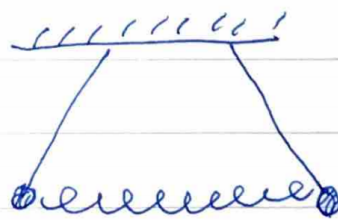
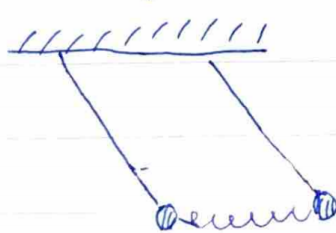
$B_1 \approx B_2$

$B_1 \approx -B_2$



Excite Mode 1
(Near ω_1)

Excite Mode 2
(Near ω_2)



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